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Pull yourself up by your bootstraps: Identifying procedural preferences against helping others in the presence of moral hazard

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Abstract

Governments and organizations often implement policies designed to help people in case of an undesirable event. Such policies can make the society better off, but they may also create moral hazard. We use a laboratory experiment to examine two questions. First, can discretionary decisions to provide assistance overcome the problem of moral hazard and lead to higher efficiency? Second, if so, will people prefer this discretionary procedure to the strict liability policy in which no assistance is provided? We find that the assistance is more efficient than the strict liability procedure. However, people still prefer the strict liability regime rather than assistance provision. We conduct additional treatments that show that this effect is not driven by the presence of the human discretion, nor by risk, loss or inequality aversion. This suggests that when moral hazard is a concern people have procedural preferences in favor of the strict liability regime.

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1. Introduction

This paper studies general preference for public provision of costly assistance to a person facing an undesirable event. We are interested in situations where the assistance is efficient (its benefits outweigh its costs) and where the effort taken to avoid the undesirable event is not observable. These situations are also characterized by moral hazard that may undermine incentives to take the unobservable precautionary measures (Ehrlich and Becker, 1972). Such situations are common and economically relevant. They include decisions to help people suffering from drug addiction (Doleac and Mukherjee, 2018) and HIV positive patients (Lakdawalla et al., 2006). They also include choices to reallocate work from one team member to another (Chan, 2016), to provide assistance to victims of natural disasters (Browne and Hoyt, 2000), or to bail out banks or companies (Farhi and Tirole, 2012).

We will use the following stylized example to guide us through this paper. Imagine a passenger arriving late at the airport. The airline faces the choice of whether to speed up her security procedures at a cost to other passengers or to have the passenger miss the flight. The late arrival of the passenger might be the result of bad luck (e.g. unexpected traffic problems) but it could also be due to negligence. Therefore, the airline's discretionary decision cannot be directly based on the level of precautions the passenger took. The discretionary decision to speed up the security procedures is likely to be efficient: the benefits of the passenger not missing the flight outweigh the costs. However, such choices also create moral hazard which could lead to an inefficient situation in which a high number of passengers arrive late.

This paper proposes an experimental design where the assistance may or may not lead to higher payoffs depending on the severity of the moral hazard problem. It introduces an effort-provision game with two regimes: *strict liability* and *assistance*. In strict liability, subjects sustain the costs created by insufficient effort or bad luck; in assistance, an official might transfer the costs to all the other participants according to a (vaguely stated) standard. In our guiding example, all passengers arriving late would miss their flight in strict liability. In assistance, the official (airline) would apply the standard to speed up the procedures of some passengers at a cost to the others.

We address two questions: First, we investigate whether the participants overcome the moral hazard problem so that assistance is more efficient in terms of monetary wealth than strict liability. Second, we test whether the participants' preferences for assistance or strict liability correspond to the respective monetary outcomes.[1] To answer these questions, each subject plays the effort-provision game in both regimes. We then let the subjects vote on which regime they preferred, and implemented the preferred regime in the last part of the experiment. The monetary efficiency of assistance in our design depends on the agent's compliance with the standard, specifying the optimal level of assistance depending on the imperfectly observed effort levels, and thus managing the moral hazard problem. We find that the monetary payoffs in the assistance regime are higher than in the strict liability regime, which means that the officials are able to enforce the standard and the moral hazard problem can be avoided. Despite this, the majority of participants voted for the strict liability regime and the preference for strict liability is confirmed by a discrete choice model which controls for payoff differences between the regimes.

Apart from the main treatment with a human official (HUMAN), we introduce two additional between-subject treatments to rule out some of the possible explanations for the preference for strict liability. This preference may be related to some more general behavioral mechanisms. People have a well-documented tendency to avoid situations in which another person determines their outcome. In a trust game, people require higher expected payoffs if there is any chance that they could be betrayed by a human opponent, compared to the equivalent game against a computer (Bohnet and Zeckhauser, 2004; Bolton and Ockenfels, 2010). In principal-agent experiments when people are asked to delegate decisions directly to someone else, they sacrifice monetary gain in order to make the decision themselves (Owens et al., 2014; Fehr et al., 2013; Bartling et al., 2014). In line with these results, the preference for the strict liability regime that our experiment reveals might be related to the presence of the human official in the assistance regime. In order to investigate this explanation, we conducted a NATURE treatment in which the human official is replaced by a known probability distribution taken from the officials' choices made in the sessions with human officials. We find that people still prefer strict liability over assistance, which means

[1] This latter question is motivated by cases of assistance programs that generate opposition, which materializes in citizen protests or elections and often leads to such programs being limited or terminated. Such protests are often driven by people feeling that these programs are arbitrary and unfair; such resentment intensifies in times of economic hardship (see e.g. the description of opposition to the Moving to Opportunity program in Goering et al., 2003).

the unpopularity of the assistance is not driven by the presence of a human official but by the liability assignment aspect of the procedure.

The preference for the assistance regime might also reflect differences in the distribution of round payoffs between these regimes: the payoffs in assistance have lower variance and fewer of them are negative. This might lead to preference for assistance if subjects are inequality, risk or loss averse. The CONTROL treatment generates the same payoff distribution for both regimes as in HUMAN and NATURE, but the subjects do not make any choices. The preference for *strict liability* is no longer present, which shows that this result is not driven by risk aversion, loss aversion or inequality aversion.

These findings about the preference for strict liability are in line with recent literature on *procedural preferences* showing that individuals value institutions and procedures for their intrinsic value. Most of this literature makes use of pie-splitting games to show that people prefer procedures that provide fair randomization over unequal outcomes (Bolton et al., 2005; Karni et al., 2008), or guarantee a kind distribution of outcomes (Sebald, 2010). Our finding, however, seems to be driven by so-called *purely procedural preferences*, i.e. preferences for procedural properties unrelated to payoffs or outcomes (Chlaß et al., 2019). Chlaß et al. (2019) documents that people consider procedural simplicity, efficiency, and distribution of the decision and information rights in their choices. In line with the notion of purely procedural preferences, Sausgruber and Tyran (2014) showed in a laboratory experiment that people prefer uniform taxes over discriminatory taxes that are equally efficient and produce the same expected outcomes. We contribute to this literature by showing that the contradiction between efficiency and preferences also applies in the case of (public) assistance in situations fraught with moral hazard. Moreover, we find that preference for the strict liability regime is correlated with deontological attitudes[2]. We interpret that correlation as suggestive evidence that the voting decision in our experiment reflects the discrepancy between efficiency and a norm that everyone should be fully liable for their own losses.

Our paper is also related to the literature on moral hazard problems in

[2]People with deontological attitudes judge an action based on whether that action is right or wrong under a set of rules, rather than based on the consequences of the action.

loss-sharing situations.[3] Besides one empirical study that documents the existence of moral hazard problems in many real-world contexts, there have been a small number of laboratory experiments examining the effects of loss-sharing on loss-reducing investment (Füllbrunn and Neugebauer, 2013; Mol et al., 2020), choice of risky lotteries (Bixter and Luhmann, 2014) and overtreatment at a credence good market (Huck et al., 2016). The experiment presented by Füllbrunn and Neugebauer (2013) is the most closely related to the current study. They consider a situation in which participants can make an investment in order to avoid losses. The experiment includes a full liability treatment, in which participants are fully liable for their loss, and a limited liability treatment in which the losses are shared equally within a group. They find that limited liability leads to lower loss-avoidance investment, however any efficiency comparison in their experiment would be trivial because individual preferences are fully aligned with social welfare in the full liability treatment. Unlike Füllbrunn and Neugebauer (2013), we study a situation in which loss-sharing is not given by a rule known in advance, but rather it depends on human discretion guided by a vaguely stated standard. Moreover, we focus on situations in which providing loss coverage has direct benefits in terms of social welfare. We contribute to the literature by investigating whether losses caused by a decrease of loss-avoidance effort outweigh the direct benefits of loss coverage.

Our experiment also resembles the determination of liability in tort law models with unilateral accident (Shavell, 2007). These models assume that the overall value of the loss does not depend on the assignment of liability. Our experimental design, on the other hand, follows the assumption that the loss is larger when the agent has to cover it by himself. Given the lack of real-world data, several experiments have been conducted to examine the relative advantages of strict liability rules and negligence standards. These papers have focused primarily on the effects of strict liability and negligence on effort levels (Kornhauser and Schotter, 1990; Angelova et al., 2014; Deffains et al., 2019). The experiment we present in this paper is different from these contributions both in terms of its aim and the experimental design. Our experimental design contains a human decision-maker in the role of an

[3]Note that our problem differs from the large literature on moral hazard in teams (Holmstrom, 1982). In teams, shirking behavior is pervasive since individual effort levels are substitutes and team members are paid according to their aggregate effort. In our case, individual effort levels are not substitutes and cannot be aggregated.

official. This is motivated by i) standards being by definition general and needing to be interpreted; ii) our focus on moral hazard, where we investigate whether human officials are able to credibly enforce the given standard. We contribute to the literature by providing evidence that ranking different liability rules based on revealed preferences does not coincide with ranking based on monetary payoffs.

The rest of this paper is structured as follows: Section 2 introduces the theoretical framework. Section 3 presents the experimental design and procedures and formulates the hypotheses tested by the experiment. Section 4 describes the data generated by the experiment. Section 5 presents the results and section 6 provides a short discussion of the results.

2. Theoretical framework

Our experiment consists of an effort provision game and a voting procedure. The effort provision game has two regimes: strict liability and assistance. These two regimes are played in the first two stages of the experiment. Voting in the third stage determines which regime will be played in the final stage. This design enables us to answer our research questions by comparing the efficiency of these regimes and preferences for them. The rest of this section discusses the theory related to our research questions.

2.1. Efficiency of regimes

First, we present the effort-provision model and compare the efficiency of the strict liability and assistance regimes. The agent chooses the effort level e. The effort is costly and the monetary costs are given by the function $c(e)$ which is increasing and non-concave, i.e. $c'(e) > 0$ and $c''(e) \geq 0$. Bad luck b is a random variable with support $[-\underline{b}, 0]$ and probability distribution function $f(b)$ which is increasing, $f'(b) > 0$. The effort level and bad luck determine whether the outcome is bad or good. A bad outcome occurs if the sum of the effort and bad luck falls below the threshold T, i.e. $b + e < T$. In our guiding example, e is the effort expended to arrive at the airport in time, such as getting up early, using more secure means of transport, etc. Bad luck can take many forms, such as the passenger facing unexpected traffic problems. The natural situation in which the passenger misses their flight unless assistance is provided constitutes the threshold.

Only the sum $b + e$ is observable to the third party. The effort itself e is not observable. If the bad outcome happens, there is a loss that needs to be covered. The loss can be covered by the agent or by the society (other agents in the group). In the former case the value of the loss is L_A, in the latter case it is L_S. We assume that $L_A > L_S$, which represents that the society as whole is better off if the loss is covered by others.[4] In our example, the airport personnel observes late arrival, but usually cannot verify to which extent the situation was caused by negligence or bad luck. L_A is the loss resulting from a missed airplane, while L_S would be the extra waiting time or other inconveniences or risks caused by speeding up the security check.

The regimes differ in the way the liability for the loss is assigned. Under the *strict liability* regime, the responsible agent always pays the loss. The *assistance* regime is complemented by a standard which states that the loss will be paid by the agent if he did not exert sufficient effort to prevent the loss. A benevolent official decides whether this requirement was met. The official can observe $e + b$, which we call observable effort. In our guiding example, the observable effort could be the arrival time of the passenger coupled with the general traffic situation known to the official.

The welfare function in this modelling framework is given by the negative value of total monetary costs

$$-Pr(b + e < T)l - c(e).$$

It comprises of three elements: i) the probability that the total effort falls below the threshold $Pr(b + e < T)$; ii) the loss l which is paid by the agent or society $l \in \{L_A, L_S\}$; iii) the costs of exerting effort $c(e)$.

We provide the solutions of the model under four different conditions: strict liability regime (SL), assistance without commitment (A), assistance with commitment (AC) and first-best solution (FB); and we compare their welfare consequences. In the strict liability regime, the loss is always paid by the agent. The agent chooses the effort level e^R in order to minimize the expected loss and effort costs. In the assistance regime with commitment, the official first chooses the standard D. If $D < e+b < T$, the official lets the society to cover the loss. In the second stage, the agent chooses the optimal effort level e^{AC}.

Note, that a benevolent and myopic official does not have to be willing to enforce the standard D. The problem is that enforcing a standard is

[4]When the losses are equal $L_S = L_A$, the first-best solution can be achieved by a simple strict liability regime.

dynamically inconsistent in a one-shot game. Once the effort decision is made and effort costs are sunk, the official is tempted to deviate from the standard and let the society pay for the loss even if the observable effort falls below D. The agent realizes this dynamic inconsistency, resulting in zero effort. This situation is labeled as assistance regime without commitment. First-best solution provides a welfare benchmark by choosing both variables l and e to maximize the welfare function.

The following proposition provides comparison of the effort and welfare levels in these four situations. The proof and details of calculations are to be found in the Supplementary material.

Proposition 2.1. *The effort levels under the different regimes rank as follows* $e^A < e^{AC} \leq e^{FB} < e^{SL}$*. The welfare under the different regimes rank as follows* $W^A < W^{SL} < W^{AC} < W^{FB}$.

Table 1 provides the equilibrium predictions given the parameters of the model used in our experiment (see Section 3).

Table 1: Equilibrium predictions

	Solution			
	SL	AC	A	FB
Effort levels (purchased tokens)	4	2	0	2
Bad outcome probability	0.14	0.38	0.74	0.38
Welfare (expected payoff)	86	88	84.5	91.5

In the experiment described in Section 3, the official is either allowed to provide assistance, i.e. to transfer the loss to other agents, or is not allowed to help. We call these two experimental regimes assistance and strict liability, respectively. While the strict liability experimental regime corresponds closely to the theoretical SL regime, the assistance choices of the officials and the reactions of the agents determine whether the outcomes of the assistance regime more closely resemble those of the theoretical AC or A regimes. The officials are instructed to assist those who are reasonably close to the threshold derived from the AC regime. We expect the agents to follow the instructions and thereby avoid the moral hazard problem and achieve outcomes close to those predicted in the AC regime. This leads to our first hypothesis:

Hypothesis 1: Effort, measured by purchased tokens, is lower in assistance than in strict liability.

The model predicts that if agents reduce the level of effort and the officials follow the instructions, AC will lead to higher monetary payoffs than SL. This generates our second hypothesis.

Hypothesis 2: The average monetary payoff is higher in assistance than in strict liability.

2.2. Preferences for regimes

Preferences between the experimental regimes of strict liability and assistance are elicited in the voting stage, where agents (not officials) vote on which of the regimes should be played in the final stage. We believe that there are several compelling reasons why, controlling for the differences in monetary payoffs, people will prefer strict liability to assistance. We therefore formulate the following conjecture about the outcome of the voting decision:

Conjecture 1: Conditional on monetary payoffs, agents prefer strict liability over assistance.

The rest of this section discusses possible explanations for the preference for strict liability as well as treatments that allow us to differentiate among them. Preference for strict liability might be driven by the presence of a human official. Ambiguity-averse subjects might want to avoid ambiguity related to the official's discretionary power to determine the outcome or they might feel betrayed if they comply with the standard and the official makes them liable for the loss. To rule these concerns out, we compare the results of the HUMAN treatment, in which the official is a human subject, with those of the NATURE treatment, which is identical to HUMAN in all aspects except that the official is played by a computer program. The computer decides according to a function that defines the probability that the loss is paid by other members of the group conditional on the observable effort. The value of probabilities was established as the fraction of choices in which the group members had to pay for the loss in the HUMAN treatment sessions. The decisions made by nature therefore mimicked the decisions of our human officials. The probabilities are presented in Table 4, and the subjects were informed about the values of these probabilities in the instructions.

Preferences for strict liability might also result from different distributions of payment in the first stages of the experiment, which consist of 15 rounds each. More specifically, in assistance, subjects are more likely to have negative payoffs and the variance of those payoffs is higher than in strict liability (see Figure 1 for the distribution of payoffs in our experiment). This might lead to a preference for strict liability if subjects are loss, risk, or inequality averse.[5] To address these concerns, we introduce an additional treatment called CONTROL, which is similar to the NATURE treatment but with one difference: subjects do not choose the effort. Instead, the number of purchased tokens is generated by the computer from the empirical distribution of purchased tokens in the NATURE and HUMAN treatments. This treatment exogenously generates the same distribution of payoffs.

Suppose the NATURE and CONTROL treatments exclude ambiguity or betrayal aversion created by official's discretionary choices, and loss, risk or inequality aversion due to the different distribution of payoffs among agents. The preference for strict liability may then be due to several other aspects of the procedure. As the CONTROL treatment rules out any reasons related to differences in expected payoffs and, ex-ante, agents expect the same equilibrium payoff in both treatments, such a preference cannot be the result of a preference for equal expected payoffs (Bolton et al., 2005; Karni et al., 2008). Next, we will discuss some of the purely procedural preferences (Chlaß et al., 2019) that might explain preference for strict liability in this situation. Note that our design does not enable us to differentiate among these explanations.

The strict liability procedure seems superior in terms of several purely procedural concerns, as discussed in Chlaß et al. (2019):

- *Transparency:* Assistance is less transparent because of the anonymized information about the round results. Agents in assistance are thus not perfectly informed about who suffered a loss and was given assistance in the previous rounds of the game. In strict liability, agent also don't know who suffered loss, but the lack of transparency in the assistance regime seems more important because it affects the payoff to all other agents.

[5] As we discuss in the subsequent section, agents receive anonymized information about other agents' payoffs, so they are not able to calculate the total payoff to other subjects (in all 15 rounds). Inequality aversion might not be an issue here if they do not expect the other subjects' payoffs to differ substantially from theirs.

- *Inequality in information:* While agents have equal information in both regimes, the official has better information in assistance and worse (no) information in strict liability. If agents prefer to have the information advantage, they will prefer strict liability.

- *Simplicity*: The strict liability procedure is simpler because agents do not need to take the official's choice into account.

Since Chlaß et al. (2019) categorize information transparency and inequality as ethical concerns, we check the ethical component of the preference for strict liability (analogously to Chlaß et al. (2019)) by correlating it with a consequentialist scale (Robinson et al., 2015).

In addition to the purely procedural concerns covered by Chlaß et al. (2019), agents might dislike their payoffs being reduced because of other agents' possible negligence. This preference is in line with the attribution hypothesis by Blount (1995). Blount's experiment shows that minimally accepted offers in an ultimatum game were higher when the proposal was made by a participant than when the proposal was selected by a random draw. Analogically, the low payoffs in certain rounds of the assistance regime could be linked to deliberately negligent choices by other agents.

3. Experimental procedure

Subjects are randomly matched into groups of five. Four subjects are given the role of *agents*, and one subject has the role of the *official*. The matching remains fixed during the whole experiment in order to strengthen the learning effect. The experiment consists of four stages: the strict liability regime, the assistance regime, the voting stage, and the final stage.

The strict liability regime has 15 periods. The officials are inactive: they do not make any decisions, and they do not get any feedback about the other agents' behaviour. At the beginning of each period, agents are endowed with 140 CZK[6] and 6 tokens. The subjects know that zero to six tokens can be lost according to a predetermined probability distribution. The probability distribution is presented in Table 2. Agents have the opportunity to buy

[6]At the time of the experiment, 1 USD was equivalent to 22 Czech Crown (CZK) and 1 EUR was equivalent 25 CZK. A standard wage of an hour of unqualified student labour was approx. 100 CZK.

zero to six additional tokens. Each token costs 10 CZK. After the buying decision is made, a random draw determines how many tokens are lost. If the number of tokens remaining is less than six, than the agent has to cover the loss 100 CZK.

Table 2: Probability distribution

Number of tokens lost	0	1	2	3	4	5	6
Probability	0.26	0.20	0.16	0.12	0.12	0.08	0.06

The assistance regime also consists of 15 periods. The only difference between the assistance regime and the strict liability regime is the active role of the officials. The officials do not observe the extent of bad luck, i.e. how many tokens were lost, they are only informed about the remaining number of tokens. If the remaining number of tokens falls below six, the official has to choose whether the loss is paid by the agent with an insufficient number of tokens or by the other three agents in the group. In the case of the former, the agent will pay 100 CZK; in the latter case, each of the other three group members pays 25 CZK. The officials were instructed that they should let the agent with less than six tokens pay for the loss if they think that (s)he bought less than two tokens. This instruction represents the standard and it was known also to the agents. After each round, subjects receive feedback about the remaining number of tokens and their own payoff. For each of the other agents, they learn about whether the remaining number of tokens was below the threshold and the decision of the official. The information about other agents is displayed in random order, so the agents and the official are not able to track the identity of other agents during the subsequent periods.

The purpose of the first two stages is twofold. First, we can test whether the assistance regime is more efficient, i.e. agents get higher monetary payoffs. Second, agents become familiar with the assistance regime and the strict liability regime. They learn what monetary payoffs can be gained in both regimes, allowing them to make a competent voting decision.[7] To be able to control for possible order effect, half of the sessions have the assistance regime first and the strict liability regime second; in the other half of the

[7]This is why the order of the voting stage is fixed. We believe that any experimenter demand effects from this order are unlikely because it is not clear from our neutral instructions what our research question is, nor which of the regimes should be preferred.

sessions the order of these two regimes is reversed.

In the voting stage, agents in each group vote on which of the regimes should be played in the final stage. The regime that receives a majority of votes is chosen in each group; if both regimes receive two votes, one of the regimes is chosen randomly (each with a 50% probability). In the final stage, the participants play according to the rules of the regime chosen in the voting stage. The number of periods in the final stage is random. After each period, there is a 0.3 probability that the game ends. The random number of periods ensures that the final stage will not take too much time and the officials, if active, will still face a trade-off between enforcing a sufficient level of effort and capturing gains by letting the group members pay for the loss.

The instructions are read aloud at the beginning of each stage and subjects follow with their own copy. The instructions use neutral language and the subjects receive the instructions for each stage separately. At any particular stage, the subjects are not informed about what will happen in the subsequent stages. At the end of the experiment, one randomly-selected period from each of the first two stages (strict liability regime, assistance regime), and the last period from the final stage are selected for payoff. The official obtains a payoff equal to the average payoff among the four agents from the selected periods, calculated separately for the assistance regime, the strict liability regime and the final stage. Note that this payment scheme provides incentives for the official to maximize the group's overall monetary wealth.

After the experiment the subjects fill in a questionnaire. Most importantly, the questionnaire includes a shorter version of the Consequentialist scale by Robinson et al. (2015), which we use to check for any ethical component in the preference for strict liability. This short version consists of 4 questions that assess endorsement of utilitarian or deontological beliefs.[8] Participants indicate how much they agree with each statement on a 5-point Likert scale. The total score ranges between 4 and 20, with higher scores showing a tendency towards a more utilitarian attitude and lower scores pointing towards a more deontological attitude. Additionally, the questionnaire contains the standard socio-demographic variables, measures of person-

[8]These questions are: "Rules and laws should only be followed when they maximize happiness."; "When deciding what action to take, the only relevant factor to consider would be the outcome of the action."; "Some rules should never be broken."; "It is never morally justified to cause someone harm."

ality traits (the Big-Five personality traits by Rammstedt and John (2007)), self-reported risk attitude (Dohmen et al., 2011) and tolerance to ambiguity (Budner, 1962).

The experiment has three treatments, which are used to rule out possible reasons for the observed preference for the strict liability regime (see Subsection 2.2 for detailed theoretical discussion). The baseline treatment HUMAN corresponds to the description above. The NATURE treatment replaces the official with a random device. If we find the preference for strict liability in NATURE, we may rule out possible ambiguity or betrayal aversion related to the official's discretionary choices. The CONTROL treatment eliminates all choices by both officials and agents, so that the agents only passively observe the outcomes in both regimes. Should the preference for strict liability be absent in CONTROL, this means that the preference for strict liability is not explained by inequality, risk or loss aversion related to differences in the outcome distribution between the regimes.

4. Data

The experiment was conducted in October 2018 at the Masaryk University Experimental Economics Laboratory (MUEEL) in Brno, Czech Republic. In total, we recruited 328 student subjects using hroot (Bock et al., 2014). The experiment environment was programmed in zTree (Fischbacher, 2007). It took about two hours and participants received 254 CZK (10 EUR) on average. There were 16 experimental sessions in total, with 6 sessions of the HUMAN treatment, 6 sessions of NATURE treatment and 4 session of the CONTROL treatment. This resulted in 24 groups (independent observations) in HUMAN, 29 in NATURE, and 23 in CONTROL.[9]

Table 3 shows the means of selected variables in the three between-subject treatments: HUMAN, NATURE and CONTROL. The table includes information about the number of subjects and sessions (also split by the order

[9]To test Hypotheses 1 and 2, we planned to collect data from a total of 50 groups in the HUMAN and NATURE treatments. Our power analysis, which was based on simulation with inputs being the distribution of purchased tokens observed in the pilot session, indicated that this would be sufficient. With $N = 50$, we found a significant difference in 98% of cases. The significance level was 5% in a paired t-test based on group averages, and N refers to the number of groups (independent observations). When using the equilibrium values of purchased tokens (see Table 1) instead of pilot data, we get a power 0.78 for $N = 50$. We collected data from 53 groups in HUMAN and NATURE.

of the first two stages), socio-demographic variables, psychological scales, and choice variables differentiated by the regime. Table 5 uses bootstrapped confidence intervals to test the effects of the two between-subject manipulations of interest. First, it shows that the order does not affect the number of tokens purchased and payoffs in either regime. It also shows that there are no significant differences between the outcomes in the HUMAN and NATURE treatments. In fact, all three treatments generate the same payoff distributions. Our computer algorithm in the NATURE treatment successfully simulates the choices made by human officials, and the setup of the CONTROL treatment successfully mimics all the choices in the HUMAN and NATURE treatments.

Table 3: Descriptive statistics

	HUMAN	NATURE	CONTROL
Subjects (sessions)	96 (6)	116 (6)	92 (4)
- Order 1: Assistance first	48 (3)	56 (3)	44 (2)
- Order 2: Strict liability first	48 (3)	60 (3)	48 (2)
Female	0.51	0.56	0.46
Age	21.3	22.0	22.4
Students of economics or business	0.63	0.69	0.62
Risk	5.28	5.43	5.54
Ambigutity scale	11.33	11.17	11.58
Consequentialist scale	8.31	8.89	8.33
BF extraversion	5.46	5.30	5.15
BF agreeableness	5.16	5.11	5.37
BF conscientiousness	5.69	5.69	5.62
BF neuroticims	5.50	5.25	5.20
BF openness	6.40	6.27	6.24
Purchased tokens			
- Assistance	2.86	2.73	2.79
- Strict liability	3.61	3.84	3.79
Monetary payoffs			
- Assistance	86.6	86.8	86.9
- Strict liability	83.5	83.9	83.8
Frequency of loss			
- Assistance	0.29	0.30	0.30
- Strict liability	0.20	0.18	0.19

5. Results

This section presents the results of the experiment, and we focus on two separate questions. First, we test whether subjects exert sufficient effort and whether monetary payoffs were higher in the assistance regime. Second, we analyse the subjects' preferences, which were elicited via voting.

5.1. Efficiency

We look at the average behavior of the officials first. Table 4 shows the probability that human officials decided that other members of the group will pay for the loss conditional on the number of remaining tokens. The stars next to the probabilities are associated with tests of the null hypothesis of the two probabilities being equal. The same probabilities were used by the computer in NATURE and CONTROL treatment. The best-response of the agents to this behavior is to purchase two tokens, which is the optimal amount under AC solution. This shows that the officials were able to enforce the standard.

Table 4: Official's behavior

Remaining tokens	5		4		3		2		1		0
Covered loss probability	0.88	$>^{**}$	0.66	$>^{***}$	0.38	$>$	0.25	$>$	0.24	$>^{**}$	0.0

Note: $^{**}p < 0.05$; $^{***}p < 0.01$

Hypothesis 1 states that fewer tokens will be purchased in the assistance regime than in the strict liability regime. Table 5 present the differences in group averages between the two regimes (assistance − strict liability) and bootstrapped confidence intervals. In the assistance regime, people in both the HUMAN and NATURE treatments purchase significantly fewer tokens (these decisions are not made in CONTROL).[10] According to Hypothesis 2, the agents' average monetary payoff is higher in the assistance regime. As

[10]We also test whether the group averages are different from the theoretical prediction, which stated that agents should purchase 4 tokens in the SL regime and 2 tokens in the AC regime. The results show that the agents have a tendency to over-invest in the assistance regime (Mann-Whitney $p < 0.001$) and slightly under-invest in the strict liability regime (Mann-Whitney $p < 0.001$). This confirms that the officials were able to overcome the moral-hazard problem and the participants exerted sufficient effort in the assistance regime.

can be seen in Table 5, the shift from the strict liability regime to the assistance regime increases the monetary payoff in both HUMAN and NATURE treatments. Both hypotheses are thus confirmed by our data.

Table 5: Mean differences in tokens and payoffs based on group averages

		Variable	
Mean differences	Partition	Purchased tokens	Monetary payoffs
Order 1 − Order 2	Assistance	−0.22 (−0.47, 0.05)	0.64 (−1.30, 2.54)
	Strict liability	0.11 (−0.13, 0.34)	1.04 (−1.23, 3.36)
HUMAN − NATURE	Assistance	0.13 (−0.21, 0.52)	−0.19 (−2.41, 1.87)
	Strict liability	−0.23 (−0.58, 0.09)	−0.4 (−2.93, 2.37)
Assistance − Strict liability	NATURE	−0.74 (−0.97, −0.52)	3.08 (0.75, 5.58)
	HUMAN	−1.11 (−1.32, −0.89)	2.85 (0.01, 5.76)

Note: The brackets report bootstrapped 95% confidence intervals. Independent observations are groups (each consisting of 60 observations = 4 agents × 15 periods).

The hypotheses are also supported by the regression models in Table 6, in which we control for individual (agent) fixed effects, and for the regimes interacting with order and treatment. The estimates are based on data from all 30 periods. The standard errors are clustered at the group level (a group consists of 120 observations, 4 agents times 30 periods). We use the Poisson regression in models 1 and 2, which explain the purchased tokens ranging from zero to six, and OLS regression in models 3 and 4. As predicted by the models, the table shows that the assistance regime leads to lower effort and higher payoffs. The interaction *Assistance* × *Order 1* is negative in model 2, which even strengthens the effect of assistance on the number of purchased tokens. Conversely, the effect on monetary payoff is weakened by the interaction with order (opposite signs), but still the effect is significant in Order 1 ($p = 0.028$ in HUMAN and $p = 0.062$ in NATURE). The variable *lost tokens* measures the number of tokens that were lost due to bad luck, a random number ranging from zero to six drawn from the distribution presented in Table 2. The number of lost tokens strongly predicts the monetary payoffs, as losing more tokens increases the probability of falling below the threshold and experiencing a loss.

5.2. Voting

As hypothesized, participants voted with a higher frequency for the less efficient strict liability regime. In the HUMAN treatment, 60% of partici-

Table 6: Efficiency of the assistance regime

	Dependent variable:			
	Purchased tokens		Monetary payoff	
	Poisson		*OLS*	
	(1)	(2)	(3)	(4)
Assistance	-0.291^{***}	-0.160^{***}	3.008^{***}	3.490^{**}
	(0.028)	(0.042)	(0.68)	(1.31)
Assistance × Order 1		-0.148^{***}		-0.82
		(0.051)		(1.39)
Assistance × NATURE		-0.108^{***}		-0.146
		(0.050)		(1.40)
Lost tokens			-10.65^{***}	-10.65^{***}
			(0.38)	(0.38)
Individual fixed effect	Yes	Yes	Yes	Yes
Observations	6,360	6,360	6,360	6,360
R^2			0.32	0.33

Note: Standard errors clustered at the group level including 120 observations (4 agents × 30 periods). $^{*}p < 0.1$; $^{**}p < 0.05$; $^{***}p < 0.01$.

pants obtained higher payoffs in the assistance regime but only 38% of them voted for the assistance regime. In the NATURE treatments, 60% of participants obtained higher payoffs in the assistance regime but only 45% of them voted for it.

Table 7 uses the following identification strategy to detect preferences for the strict liability regime. Assume that agents have a utility function

$$U_i(m_i, S) = \alpha_0 S + \alpha_1 m_i + \epsilon_i,$$

where m is the monetary payoff of the agent, S is a dummy variable which takes the value one in the assistance regime and ϵ_i is the unobserved portion of the utility. Based on the voting decision and actual payoffs in the first two stages of the experiment, we can use discrete choice techniques to identify the parameters α_0 and α_1. The parameter α_0 is interpreted as an alternative-specific constant indicating the utility of the assistance regime not related to monetary payoff. Negative values of this parameter suggest preference in favor of strict liability. The dependent variable *Voting* takes a value of one if the agent voted for the assistance regime and zero if (s)he voted for the strict liability regime. The variable *Payoff difference* is the difference in the participants' average payoff between the assistance regime and the strict liability regime. The variable *HUMAN* represents an alternative-specific variable that measures the intrinsic utility of the assistance regime in the HUMAN treatment. The variables *NATURE* and *CONTROL* measure the same intrinsic utility in the NATURE and CONTROL treatments. We also control for the order effect and the interactions of order with payoff difference and treatments.

Two main results stand out from model 1 in Table 7. First, there is a significant and substantial preference for the strict liability regime. The average willingness to pay for avoiding the assistance regime the in HUMAN treatment is around 12 CZK (calculated as a ratio of the parameters *HUMAN/Payoff difference* from column 1 of Table 7), which is approximately four times the average payment difference between the regimes. Second, the relative unfavorability of the assistance regime is not driven solely by the presence of a human official. The preference for the strict liability regime is present even in the NATURE treatment. Although the presence of a human official makes the strict liability preference stronger, there is no statistical difference between the HUMAN and NATURE treatments. The average marginal effect of the human official is 0.061 ($p = 0.332$).

It is conceivable that our participants voted against the assistance regime because their monetary preferences are not fully captured by the difference in payoff between the strict liability and assistance regimes. Their voting decisions might be driven by the fact that they are risk averse, loss averse or inequality averse. Indeed, the distribution of monetary payoffs in the assistance regime has not only a higher mean but also larger support. The minimum possible value of monetary payoff in the strict liability regime is -10 (the participant purchases 5 additional tokens and loses 6 tokens), while in the assistance regime it is -85 (the participant purchases 5 additional tokens, loses 6 tokens and pays an extra 75 in external costs). Figure 1 shows the actual distribution of monetary payments in the assistance and strict liability regimes, and confirms that the payoff distributions are different (K-S test $p < 0.001$) with the assistance regime having larger support. Although we control the payment difference between the regimes, this may not be sufficient since risk-averse or loss-averse agents might take the whole monetary payoff distribution into account when making their voting decisions.

In order to address this concern, we look at voting decisions in the CONTROL treatment. Recall that the CONTROL treatment exogenously gener-

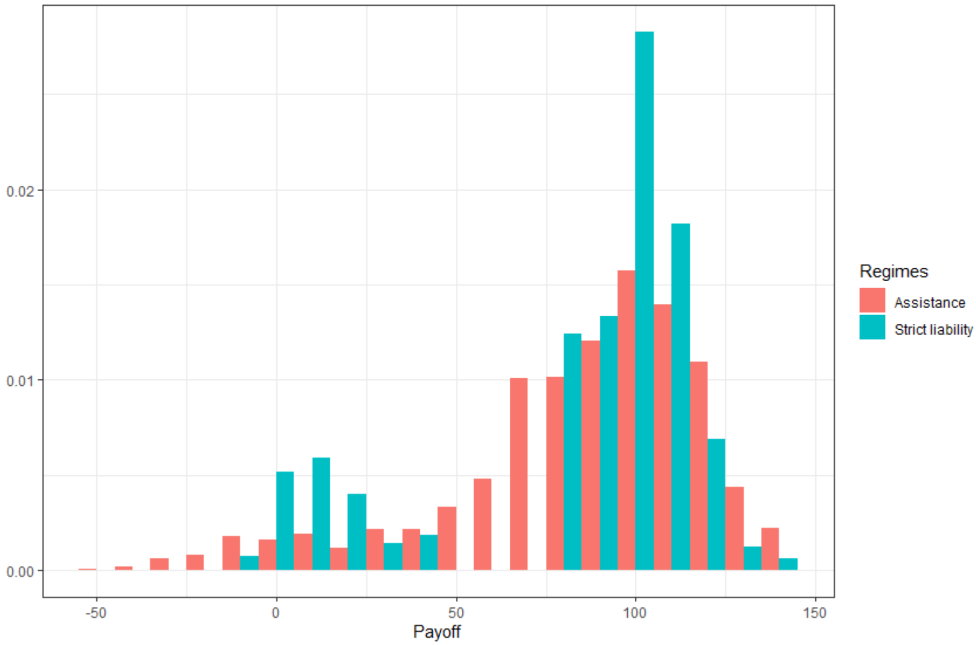
Table 7: Logit model explaining voting decision

	Dependent variable: Voting		
	(1)	(2)	(3)
HUMAN	-0.768^{***}	-0.688^{**}	-0.680^{**}
	(0.265)	(0.339)	(0.330)
NATURE	-0.474^{**}	-0.592^{**}	-0.578^{***}
	(0.215)	(0.234)	(0.217)
CONTROL	0.060	0.245	
	(0.292)	(0.371)	
Payoff difference	0.066^{***}	0.058^{***}	0.054^{***}
	(0.012)	(0.014)	(0.016)
Order 1	0.129	−0.216	0.327
	(0.244)	(0.528)	(0.331)
Payoff difference × Order 1		0.017	0.013
		(0.024)	(0.026)
HUMAN × Order 1		0.191	−0.262
		(0.656)	(0.535)
NATURE × Order 1		0.576	
		(0.611)	
Consequentialist			0.251^{**}
			(0.128)
Observations	304	304	212

Note: Standard errors clustered at the group level (group includes 4 agents). $^{*}p < 0.1$; $^{**}p < 0.05$; $^{***}p < 0.01$.

ates the same payoff distribution as the NATURE or HUMAN treatments. Subjects in the CONTROL treatment then simply reveal their preference for the payoff distribution generated by the assistance regime or by the strict liability regime. If these participants only cared about monetary payoffs and the probabilities of securing them, the voting results in the CONTROL treatment should be the same as those found in the NATURE and HUMAN treatments. However, procedural preference may create a wedge between the voting decisions. The coefficient for the CONTROL treatment shows that preference for the strict liability regime completely disappears in this treatment. Participants in the NATURE and HUMAN treatments voted significantly more often for the strict liability regime. The average marginal effect is 0.18 for the HUMAN treatment ($p = 0.011$) and 0.12 for the NA-

Figure 1: Histogram of payoffs in the assistance and strict liability regimes.



TURE treatment ($p = 0.082$). We do not observe any order effects. This result shows that participants' preference for the strict liability regime is not driven by risk-aversion, loss-aversion or any other preferences related to the payoff distribution. Overall, the results suggest that it is the strict liability aspect common to both the NATURE and HUMAN treatments that makes the strict liability regime preferable.

The model in column 3 uses data from the HUMAN and NATURE treatments, where we identify the preference for strict liability. It explores the correlation between preference for strict liability and the consequentialist scale standardized to have mean 0 and standard deviation 1. We can see that the consequentialist scale is related to preference for strict liability. People who agree more with the position that some rules should be honoured in all circumstances were more likely to vote for the strict liability regime. People who are extreme utilitarians (i.e. two standard deviations from the mean) did not manifest this preference. Using the specification of model 3, we estimated an additional seven models with other survey measures (risk, ambiguity scale, and big-five scales) instead of *Consequentialist*, but we found that none of these measures were significantly related to voting.

6. Discussion

Societies and organizations implement many policies that prevent any individual from suffering a loss or falling into hardship. Such policies face the challenge of recognizing whether the individual has suffered a loss due to bad luck or through his/her own negligence. Although some signals about a given agent's negligence are usually available, we focus on situation when it is not possible to design a rule that describes the complex nature of those signals and specifies how the policy decision should depend on them. However, human officials are able to observe those signals and decide on assistance provision. Our experiment investigates whether the discretion of such officials, guided by a negligence standard, makes the society better off compared to the strict liability regime. We consider two dimensions of what it means to be better off: higher monetary payoffs and revealed preferences elicited through a vote.

We find that assistance provision guided by a general negligence standard leads to higher monetary payoffs than strict liability. This result shows that non-verifiable information can be valuable in moral hazard situations. Standard contract theory argues that an optimal contract in moral hazard situations should condition payoffs on verifiable outcomes correlated with effort provision. The non-verifiable information can be valuable only if it can be truthfully reported to a third party Hart and Moore (1999); Maskin and Moore (1999). In our experiment we assume that the information is observable by a third party, but it cannot enter the contract or legal norm. The solution in this case might be to set a vaguely stated standard and grant decision-making power to an official who can observe the non-verifiable information.

More interestingly, the experiment provides evidence, based on revealed preferences, that people prefer the strict liability regime over assistance regime. Our results further demonstrate that this preference for strict liability cannot be fully explained by the presence of a human official and that the preference for strict liability vanishes when the agent cannot influence the level of effort and therefore the probability of loss occurring. This suggests that the preference for strict liability is procedural and seems to be related to people's aversion to having their payoff influenced by other, possibly negligent, agents and a (random) mechanism allocating the loss to everyone else but the negligent agent. This conclusion is supported by the fact that this preference is positively correlated with deontological attitudes. People with utilitarian attitudes do not exhibit any preference for the strict liability regime.

These results suggest that people might be reluctant to vote for policies that offer costly assistance to people who are at least partly responsible for their misfortunes. This finding is consistent with experimental evidence (Lefgren et al., 2016) and with the positive cross-country correlation between social spending and the belief that luck is the main factor determining income (Alesina et al., 2001). Our results complement these findings by showing that, within the specific setup we study, people do not favor policies that provide costly assistance even when those policies lead to higher monetary wealth for them and for society as a whole.

One obvious limitation of this research is the composition of our sample, which consisted exclusively of Czech students; this raises the question of how generalizable our results are. Since we find that preferences for strict liability are correlated with consequentialist attitudes, we believe that the results can be generalized at least for any population that has a similar composition of utilitarian vs. deontological attitudes. On the other hand, the aversion to the assistance regime that we identified might disappear in populations with more utilitarian attitudes. Cross-culture comparisons of consequentialist attitudes are scarce. To obtain at least an indicative idea of how utilitarian the Czech population is compared to other countries, we can look at the data from a world-wide moral machine project (Awad et al., 2018) that gathers preferences regarding the moral decisions made by self-driving cars. In particular, we focus on the extent to which people are willing to spare those who cross the road legally compared to those who cross the road on a red light. This decision is close to the deontological vs. utilitarian distinction, since it considers punishing people heavily for a minor offense. It shows that Czechs have views close to the average for the sample of 130 countries in terms of the probability of sparing rule-followers[11].

[11]The country-level average causal effect of lawful behavior on being spared is 0.352. Standard deviation is 0.044. The causal effect for the Czech Republic is 0.374, which is half a standard deviation from the mean.

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Supplementary material

First-best solution

The first-best solution is given as a solution of the following problem, where a benevolent dictator maximizes the welfare function by choosing the effort level e and variable $l \in \{L_S, L_A\}$ which determines who is responsible for the loss

$$\max_{e,l} -Pr(b + e < T)l - c(e).$$

In the first-best solution, the loss is always paid by the society, i.e. $l = L_S$ and the first-best effort level is given by the following first order condition

$$f(T - e^{FB})L_S = c'(e^{FB}). \quad (1)$$

Strict liability regime

In the strict liability regime, the agent always pays the costs whenever the sum of his effort and bad luck falls below the threshold T. Hence, the official chooses effort level that maximizes his own payoff

$$\max_{e} -Pr(b + e < T)L_A - c(e).$$

The solution of the problem is given by the following first order condition that implicitly defines the optimal effort under the strict liability regime e^{SL}.

$$f(T - e^{SL})L_A = c'(e^{SL}) \quad (2)$$

This paper only considers situations in which strict liability is a better outcome than a situation in which the agent does not exert any effort and the loss is always paid by the society. This is assured by the following assumption:

$$-Pr(b < T)L_S < -Pr(b + e^{SL} < T) - c(e^{SL}) \quad (3)$$

If this assumption does not hold, there would be no need to consider the strict liability regime at all. Instead, the paper would be reduced to a discussion of whether the identified optimal threshold level of $b + e$ for the assistance should be applied.

Assistance regime without commitment

In the assistance regime without commitment, the official's reaction function is to let the society always pay the loss $l = L_S$ and the agent's optimal effort level is equal to zero, $e^A = 0$.

Assistance regime with commitment

In the assistance regime with commitment, the agent chooses the effort level that maximizes his own payoff

$$\max_{e} -Pr(b+e<D)L_A - c(e).$$

The solution of the problem is given by the following condition

$$f(D-e^*)L_A = c'(e^*). \tag{4}$$

This condition implicitly defines the agent's best-response function $e^*(D)$. By applying the implicit function theorem we can derive the slope of this best-response function

$$e^{*\prime}(D) = \frac{f'(D-e)L_A}{f'(D-e)L_A + c''}.$$

Since the cost function is non-concave, i.e. $c'' \geq 0$, the slope is positive but less or equal to one, $e^{*\prime}(D) \in (0,1]$. The official chooses the threshold D in order to maximize the welfare function given the agent's best-response function[12].

$$\max_{D} -Pr(b+e^*<D)L_A - Pr(D<b+e^*<T)L_S - c(e^*) \tag{5}$$

The solution of this problem is given by the following first order condition

$$f(T-e)\,e^{*\prime}\,L_S - f(D-e)(1-e^{*\prime})(L_A-L_S) = c'(e)\,e^{*\prime}. \tag{6}$$

Proof of effort ranking

It follows from the first-order conditions that $e^S = 0$ and the condition (3) ensures that $e^{AC} > 0$. This proves that $e^{AC} > e^A$. By comparing the first order conditions (1) and 2, we can see that the last inequality $e^{FB} < e^{SL}$ holds. The optimal effort level e^{AC} satisfies the condition (6) which can be rewritten as $-\frac{1-e'}{e'} f(D-e^{AC})(L_A-L_S) + f(T-e^{AC})L_s = c'$. Now, suppose by contradiction that $e^{AC} > e^{FB}$. The condition (1) together with the assumptions that marginal cost are non-decreasing $c' \geq 0$ and the probability

[12]The officials problem with N agents would be the same since all agents have the same best-response function

function is increasing $f' > 0$ imply that $f(T - e^{AC})H_s < c'$. For the condition (6) to be satisfied, it has to be the case that $\frac{1-e'}{e'} f(D - e^{AC})(L_A - L_S)$ is negative. This cannot be true since the slope of the best-response function e' is positive. Hence, we have a contradiction which proves the second inequality $e^{AC} \leq e^{FB}$.

Proof of welfare ranking

The first inequality $W^A < W^{SL}$ holds by assumption (3). The prove the second inequality $W^{SL} < W^{AC}$ consider the welfare in a assistance regime with commitment as a function of the assistance threshold $W(D) = -Pr(b + e^* < D)L_A - Pr(D < b + e^* < T)L_S - c(e^*)$ where e^* is given by the condition (6). The welfare W^{AC} is the maximum value of the welfare function $W(D)$ given by problem (5). The welfare in strict liability regime is a equal to this welfare evaluated at T, i.e. $W^{SL} = W(T)$. Therefore, we only need to show that the inequality is strict. When we calculate the first derivative of the welfare and plug-in for c' from condition (6) we get $f(T - e)\, e^{*\prime}\, L_S - f(D - e)(1 - e^{*\prime})(L_A - L_S) = f(D - e)L_A\, e^{*\prime}$. By evaluating the first derivative as point T we have $-f(T - e)\,(L_A - L_S) < 0$. Since the welfare function is decreasing at T, it holds that $W^{AC} > W^{SL}$. The third inequality $W^{AC} < W^{FB}$ also holds as strict because it cannot be simultaneously the case that $D = 0$ and $e^{AC} = e^{FB}$.

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